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Table of Contents. 1.
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time control input
with zero order hold
applied to a
continuous time
system. $G_k(j) = 1/H_u(j)$:
(11) For stability, the
eigenvalues of G_m must

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have magnitude < 1 .
So if the continuous
time plant is stable ($\text{eig}(A) < 0$) the
discrete time plant
will have eigenvalues
with magnitude less
than 1.

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The time interval
between two discrete
instants is taken to be

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sufficiently short that the data for the time between them can be approximated by simple interpolation. Discrete-time control systems differ from continuous-time control systems in that signals for a discrete-time control system are in sampled-data form or in digital form.

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consists of four major

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Lecture: Discrete-
time linear systems
Sampling continuous-
time systems. Exact
sampling. Rule of

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thumb: $T_s \approx 0.1 \cdot 10$ of
the rise time = time
to move from 10% to
90% of the steady-
state value, for input
 $u(t) = 1, x(0) = 0$.

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A control system is a control system in which one or more variables can change only at discrete instants of time. These instants which are denoted by t_k or Tk , $k = 0, 1, 2, \dots$, specify the times at which some physical measurements are performed. The time interval between two discrete

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